

# A decision algorithm for strong rational general solutions of algebraic ordinary differential equations

*Franz Winkler*<sup>1</sup>

[franz.winkler@risc.jku.at]

<sup>1</sup> Research Institute for Symbolic Computation (RISC), Johannes Kepler University Linz, Linz, Austria

We consider first-order algebraic ordinary differential equations (AODEs) and study their rational general solutions. A rational general solution of a first-order AODE contains an arbitrary constant. In case the constant appears rationally, we call the solution strong. We present an algorithm for deciding the existence of a strong rational general solution of a first-order AODE, and in the positive case, compute such a solution. The problem of computing a rational general solution of first-order AODEs has not yet been solved in full generality. Our method is based on optimal parametrizations of algebraic curves over the field of rational functions.

Consider the first-order AODE,

$$F(x, y, y') = 0,$$

where  $F$  is an irreducible polynomial in three variables over an algebraically closed field  $\mathbb{K}$ . Replacing  $y'$  by a new indeterminate  $z$ , we obtain an algebraic equation  $F(x, y, z) = 0$ . This algebraic equation defines a plane algebraic curve

$$\mathcal{C} := \{(a, b) \in \mathbb{A}^2(\overline{\mathbb{K}(x)}) \mid F(x, a, b) = 0\}$$

over the field  $\overline{\mathbb{K}(x)}$  of algebraic functions. We call it the corresponding algebraic curve. A parametrization of  $\mathcal{C}$  is a rational map

$$\mathcal{P} : \mathbb{A}^1(\overline{\mathbb{K}(x)}) \rightarrow \mathcal{C} \subset \mathbb{A}^2(\overline{\mathbb{K}(x)}),$$

such that the image of  $\mathcal{P}$  is dense in  $\mathcal{C}$  with respect to the Zariski topology. If furthermore  $\mathcal{P}$  is a birational equivalence, it is called a proper parametrization. A parametrization is represented as a pair of rational functions, say  $\mathcal{P} = (p_1(t), p_2(t))$ , with coefficients in  $\overline{\mathbb{K}(x)}$ . The field which extends  $\mathbb{K}(x)$  by coefficients of  $\mathcal{P}$  is called the field of coefficients of  $\mathcal{P}$ . In case the degree of the field of coefficients over  $\mathbb{K}(x)$  is as small as possible, we call  $\mathcal{P}$  an optimal parametrization. It is well known that the field of coefficients of an optimal parametrization has at most algebraic extension degree 2 over  $\mathbb{K}(x)$ .

A rational solution of the differential equation  $F(x, y, y') = 0$  is a rational function  $y(x) \in \mathbb{K}(x)$ , such that  $F(x, y(x), y'(x)) = 0$ . According to Ritt [1] the radical differential ideal  $\{F\}$  can be decomposed as

$$\{F\} = \underbrace{\left(\{F\} : \frac{\partial F}{\partial y'}\right)}_{\text{general component}} \cap \underbrace{\left\{F, \frac{\partial F}{\partial y'}\right\}}_{\text{singular component}} .$$

$S$  is the separant of  $F$ , i.e., the derivative of  $F$  w.r.t.  $y^{(n)}$ . Ritt shows that the general component is a prime differential ideal; its generic zero is called a *general solution* of the AODE  $F(x, y, y') = 0$ . Such a general solution must contain a transcendental constant  $c$ . In [2, 3] we have presented a method for determining rational general solutions of first-order AODEs. This method is based on rational parametrization of surfaces. Whereas it can determine rational general solutions for almost all parametrizable first-order AODEs, it is not a decision algorithm.

Here we are a little more modest, and we aim at determining so-called strong rational general solutions. A solution  $y(x)$  of the AODE is called a *strong rational general solution*, if  $y = y(x, c) \in \mathbb{K}(x, c) \setminus \mathbb{K}(x)$ , where  $c$  is a transcendental constant over  $\mathbb{K}(x)$ . So a strong rational general solution is a proper rational function in  $x$  and  $c$  over  $\mathbb{K}$ .

The key fact which allows to decide the existence of strong rational general solutions, and in the positive case compute them, is the following:

**Theorem** *Let  $F \in \mathbb{K}(x)[y, z]$  be an irreducible polynomial. If the algebraic curve in  $\mathbb{A}^2(\overline{\mathbb{K}(x)})$  defined by  $F = 0$  is a rational curve, then the coefficient field of its optimal parametrization is always  $\mathbb{K}(x)$ .*

A full description of this decision method can be found in [4].

### Keywords

ordinary differential equation , algebraic curve, rational parametrization, rational general solution

### References

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